

DFS60B-THAK00S96

DFS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.

Illustration may differ

Ordering information

| Type | part no. |
|------------------|----------|
| DFS60B-THAK00S96 | 1088235 |

Other models and accessories → www.sick.com/DFS60



Detailed technical data

Features

| | |
|----------------------------------|---|
| Special device | ✓ |
| Specialty | Cable, 8-wire, universal, 1.5 m, customized cable connection (10 cm braided shield) |
| Standard reference device | DFS60B-THAK10000, 1058444 |

Safety-related parameters

| | |
|--|--|
| MTTF_D (mean time to dangerous failure) | 300 years (EN ISO 13849-1) ¹⁾ |
|--|--|

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

| | |
|---|-------------------------------------|
| Pulses per revolution | 10,000 ¹⁾ |
| Measuring step | 90°, electric/pulses per revolution |
| Measuring step deviation at non binary number of lines | ± 0.01° |
| Error limits | ± 0.05° |

¹⁾ See maximum revolution range.

Interfaces

| | |
|---------------------------------------|----------------------|
| Communication interface | Incremental |
| Communication Interface detail | TTL / RS-422 |
| Number of signal channels | 6-channel |
| Initialization time | 40 ms |
| Output frequency | ≤ 600 kHz |
| Load current | ≤ 30 mA |
| Operating current | 40 mA (without load) |

Electronics

| | |
|-------------------------------|---|
| Connection type | Special version |
| Connection type Detail | Cable, 8-wire, universal, 1.5 m, customized cable connection (10 cm braided shield) |

¹⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

| | |
|--|---|
| Supply voltage | 4.5 ... 5.5 V |
| Reference signal, number | 1 |
| Reference signal, position | 90°, electric, logically gated with A and B |
| Short-circuit protection of the outputs | ✓ ¹⁾ |

¹⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

Mechanics

| | |
|---------------------------------------|---|
| Mechanical design | Through hollow shaft |
| Shaft diameter | 15 mm Front clamp |
| Weight | + 0.2 kg |
| Shaft material | Stainless steel |
| Flange material | Aluminum |
| Housing material | Aluminum die cast |
| Start up torque | 0.8 Ncm (+20 °C) |
| Operating torque | 0.6 Ncm (+20 °C) |
| Permissible movement static | ± 0.3 mm (radial) ± 0.5 mm (axial) |
| Permissible movement dynamic | ± 0.1 mm (radial) ± 0.2 mm (axial) |
| Operating speed | ≤ 6,000 min ⁻¹ ¹⁾ |
| Moment of inertia of the rotor | 40 gcm ² |
| Bearing lifetime | 3.6 x 10 ¹⁰ revolutions |
| Angular acceleration | ≤ 500,000 rad/s ² |

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

| | |
|--------------------------------------|--|
| EMC | According to EN 61000-6-2 and EN 61000-6-3 |
| Enclosure rating | IP65, housing side, cable connection (IEC 60529) IP65, shaft side (IEC 60529) |
| Permissible relative humidity | 90 % (Condensation not permitted) |
| Operating temperature range | -40 °C ... +100 °C ¹⁾ -30 °C ... +100 °C ²⁾ |
| Storage temperature range | -40 °C ... +100 °C, without package |
| Resistance to shocks | 70 g, 6 ms (EN 60068-2-27) |
| Resistance to vibration | 30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6) |

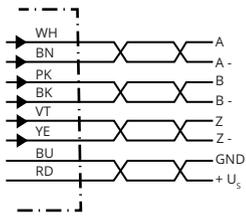
¹⁾ Stationary position of the cable.

²⁾ Flexible position of the cable.

Certificates

| | |
|---|---|
| EU declaration of conformity | ✓ |
| UK declaration of conformity | ✓ |
| ACMA declaration of conformity | ✓ |
| Moroccan declaration of conformity | ✓ |
| China RoHS | ✓ |

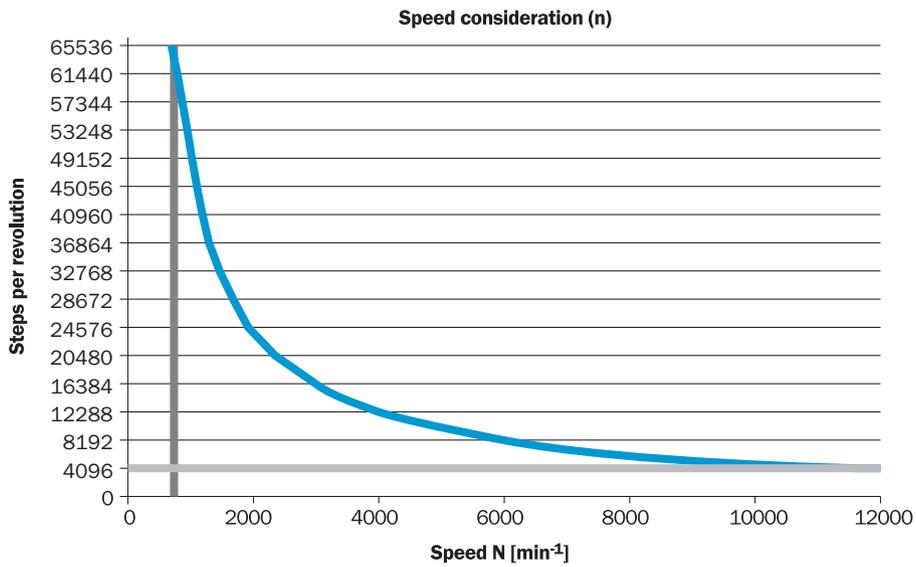
PIN assignment



| PIN Male connector M12, 8-pin | PIN Male connector M23, 12-pin | Wire colors (cable connection) | TTL/HTL signal | Sin/Cos 1.0 V _{PP} | Explanation |
|-------------------------------|--------------------------------|--------------------------------|---------------------|-----------------------------|---|
| 1 | 6 | Brown | \bar{A} | COS- | Signal wire |
| 2 | 5 | White | A | COS+ | Signal wire |
| 3 | 1 | Black | \bar{B} | SIN- | Signal wire |
| 4 | 8 | Pink | B | SIN+ | Signal wire |
| 5 | 4 | Yellow | \bar{Z} | \bar{Z} | Signal wire |
| 6 | 3 | Purple | Z | Z | Signal wire |
| 7 | 10 | Blue | GND | GND | Ground connection |
| 8 | 12 | Red | +U _S | +U _S | Supply voltage |
| - | 9 | - | N.c. | N.c. | Not assigned |
| - | 2 | - | N.c. | N.c. | Not assigned |
| - | 11 | - | N.c. | N.c. | Not assigned |
| - | 7 ¹⁾ | Orange | 0-SET ¹⁾ | N.c. | Set zero pulse ¹⁾ |
| Screen | Screen | Screen | Screen | Screen | Screen connected to housing on encoder side. Connected to ground on control side. |

¹⁾For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

maximum revolution range



SICK AT A GLANCE

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Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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