

DFS60B-S1PK00S04

DFS60

INCREMENTAL ENCODERS





Ordering information

Туре	part no.
DFS60B-S1PK00S04	1116291

Other models and accessories → www.sick.com/DFS60





Detailed technical data

Features

Special device	✓
Specialty	Pulses per revolution: preprogrammed to 3600 HTL preprogrammed
Standard reference device	DFS60B-S1PK10000, 1036757

Safety-related parameters

MTTF _D (mean time to dangerous failure)	300 years (EN ISO 13849-1) 1)
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	3,600 ¹⁾
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°

 $^{^{1)}}$ See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	HTL / Push pull
Factory setting	Factory setting output level HTL
Number of signal channels	6-channel
Programmable/configurable	✓
Initialization time	32 ms, 30 ms ¹⁾
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.7 W (without load)

 $^{^{1)}}$ With mechanical zero pulse width.

Electronics

Connection type	Cable, 8-wire, universal, 1.5 m ¹⁾
Supply voltage	4.5 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ^{2) 3)}

 $^{^{1)}}$ The universal cable connection is positioned so that it is possible to lay it without bends in a radial or axial direction.

Mechanics

Mechanical design	Solid shaft, Servo flange
Shaft diameter	6 mm With flat
Shaft length	10 mm
Weight	+ 0.3 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.5 Ncm (+20 °C)
Operating torque	0.3 Ncm (+20 °C)
Permissible shaft loading	80 N (radial) 40 N (axial)
Operating speed	≤ 9,000 min ^{-1 1)}
Moment of inertia of the rotor	6.2 gcm ²
Bearing lifetime	3.6 x 10^10 revolutions
Angular acceleration	≤ 500,000 rad/s²

 $^{^{1)}}$ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67, housing side, cable connection (IEC 60529) IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C +100 °C ¹⁾ -30 °C +100 °C ²⁾
Storage temperature range	-40 °C +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz 2,000 Hz (EN 60068-2-6)

 $^{^{1)}}$ Stationary position of the cable.

Certificates

EU declaration of conformity	✓
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Programming TTL with \geq 5.5 V: short-circuit opposite to another channel or GND permissable for maximum 30 s.

 $^{^{3)}}$ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissable for maximum 30 s.

²⁾ Flexible position of the cable.

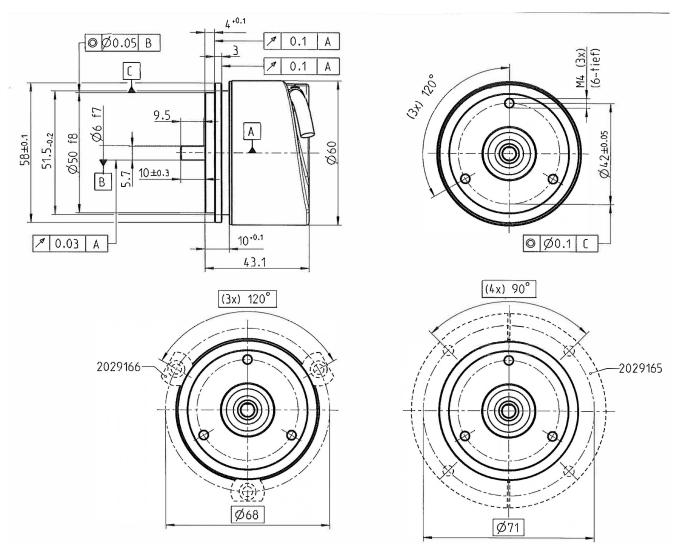
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UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓
China RoHS	✓
cULus certificate	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

Classifications

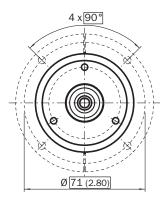
ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing



Dimensions in mm (inch)

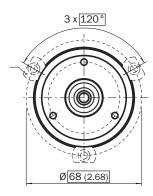
Mounting requirements for half-shell servo clamp



All dimensions in mm (inch)

part no. 2029165

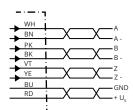
Mounting requirements for small servo clamp



All dimensions in mm (inch)

part no. 2029166

PIN assignment



Screen

PINMale connec-PINMale connec-Wire colors (ca-TTL/HTL signal Sin/Cos 1.0 V_{PP} **Explanation** tor M12, 8-pin tor M23, 12-pin ble connection) __A 1 6 Brown COS-Signal wire 2 5 White Α COS+ Signal wire __В 3 1 Black SIN-Signal wire 4 8 Pink В SIN+ Signal wire 5 4 Yellow -z -z Signal wire 6 3 Purple Ζ Ζ Signal wire 7 10 Blue **GND GND** Ground connection 8 12 Red $+U_S$ +U_S Supply voltage 9 N.c. N.c. Not assigned

N.c.

N.c.

0-SET 1)

Screen

N.c.

N.c.

N.c.

Screen

Orange

Screen

2

11

7 1)

Screen

Not assigned

Not assigned

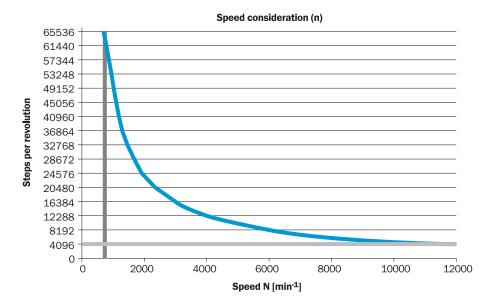
Set zero pulse¹⁾

Screen connect-

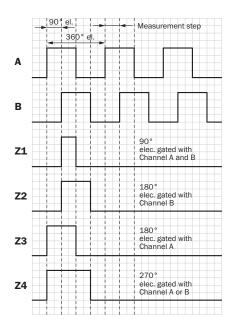
ed to housing on encoder side. Connected to ground on control side.

¹⁾For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

maximum revolution range



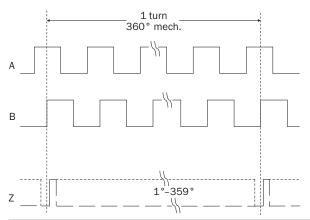
Diagrams Electrical zero pulse width can be configured to 90° , 180° , or 270° . Width of the zero pulse in relation to a pulse period.



Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V 32 V	TTL/HTL programmable

Diagrams Mechanical zero pulse width 1° to 359° programmable. Width of the zero pulse in relation to a mechanical revolution of the shaft.



Supply voltage	Output
4,5 V 32 V	TTL/HTL programmable

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