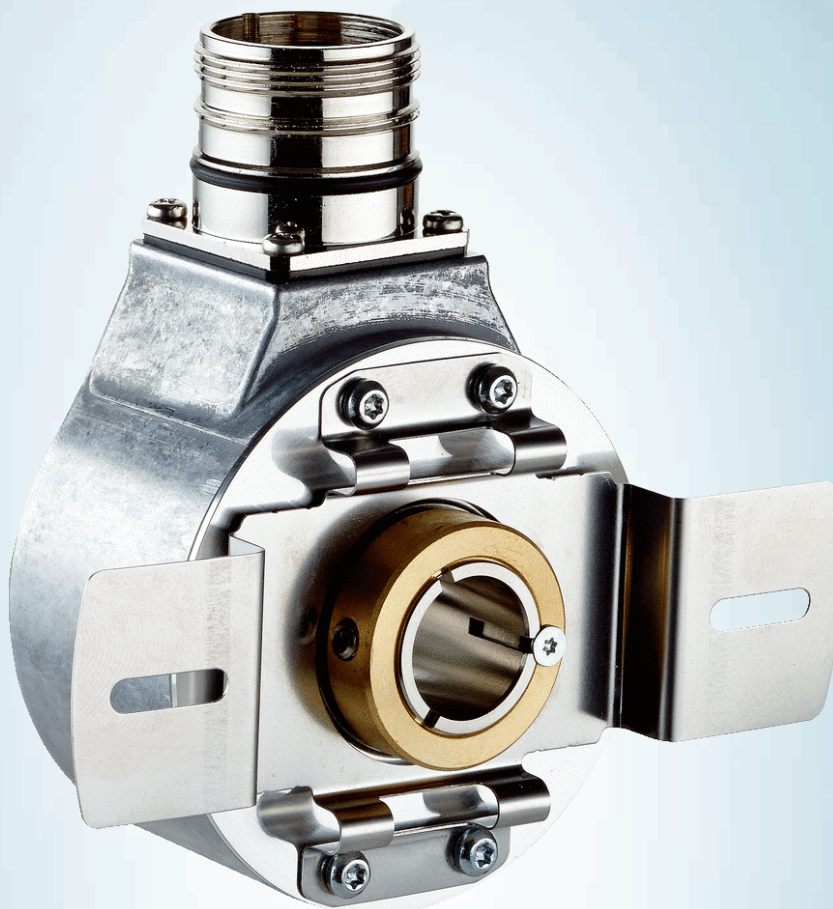




DBS60E-TECA02048

DBS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	part no.
DBS60E-TECA02048	1135754

Other models and accessories → www.sick.com/DBS60

Detailed technical data

Safety-related parameters

MTTF_D (mean time to dangerous failure)	500 years (EN ISO 13849-1) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	2,048
Measuring step	≤ 90°, electric/pulses per revolution
Measuring step deviation	± 18° / pulses per revolution
Error limits	Measuring step deviation x 3
Duty cycle	≤ 0.5 ± 5 %

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / RS-422
Number of signal channels	6-channel
Initialization time	< 5 ms ¹⁾
Output frequency	+ 300 kHz ²⁾
Load current	≤ 30 mA, per channel
Power consumption	≤ 0.5 W (without load)

¹⁾ Valid signals can be read once this time has elapsed.

²⁾ Up to 450 kHz on request.

Electronics

Connection type	Male connector, M23, 12-pin, radial
Supply voltage	10 ... 30 V

¹⁾ Short-circuit opposite to another channel or GND permissible for max. 60 s. No protection signal against U_S.

Reference signal, number	1
Reference signal, position	90 °, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ¹⁾

¹⁾ Short-circuit opposite to another channel or GND permissible for max. 60 s. No protection signal against U_S.

Mechanics

Mechanical design	Through hollow shaft
Shaft diameter	12 mmFront clamp
Flange type / stator coupling	2-sided stator coupling, slot, screw hole circle 63–83 mm
Weight	+ 0.25 kg ¹⁾
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum
Start up torque	+ 0.5 Ncm (+20 °C)
Operating torque	0.4 Ncm (+20 °C)
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial) ²⁾
Permissible movement dynamic	± 0.1 mm (radial) ± 0.2 mm (axial) ²⁾
Operating speed	6,000 min ⁻¹ ³⁾
Maximum operating speed	9,000 min ⁻¹ ⁴⁾
Moment of inertia of the rotor	50 gcm ²
Bearing lifetime	3.6 x 10 ⁹ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Based on encoder with male connector or cable with male connector.

²⁾ Not applicable for stator coupling type C and K.

³⁾ Allow for self-heating of 2.6 K per 1,000 rpm when designing the operating temperature range.

⁴⁾ Maximum speed which does not cause mechanical damage to the encoder. Impact on the service life and signal quality is possible. Please note the maximum output frequency.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, housing side (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	–30 °C ... +100 °C, at maximum 3,000 pulses per revolution ²⁾
Storage temperature range	–40 °C ... +100 °C, without package
Resistance to shocks	250 g, 3 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

¹⁾ With mating connector fitted.

²⁾ These values relate to all mechanical versions including recommended accessories unless otherwise noted.

Certificates

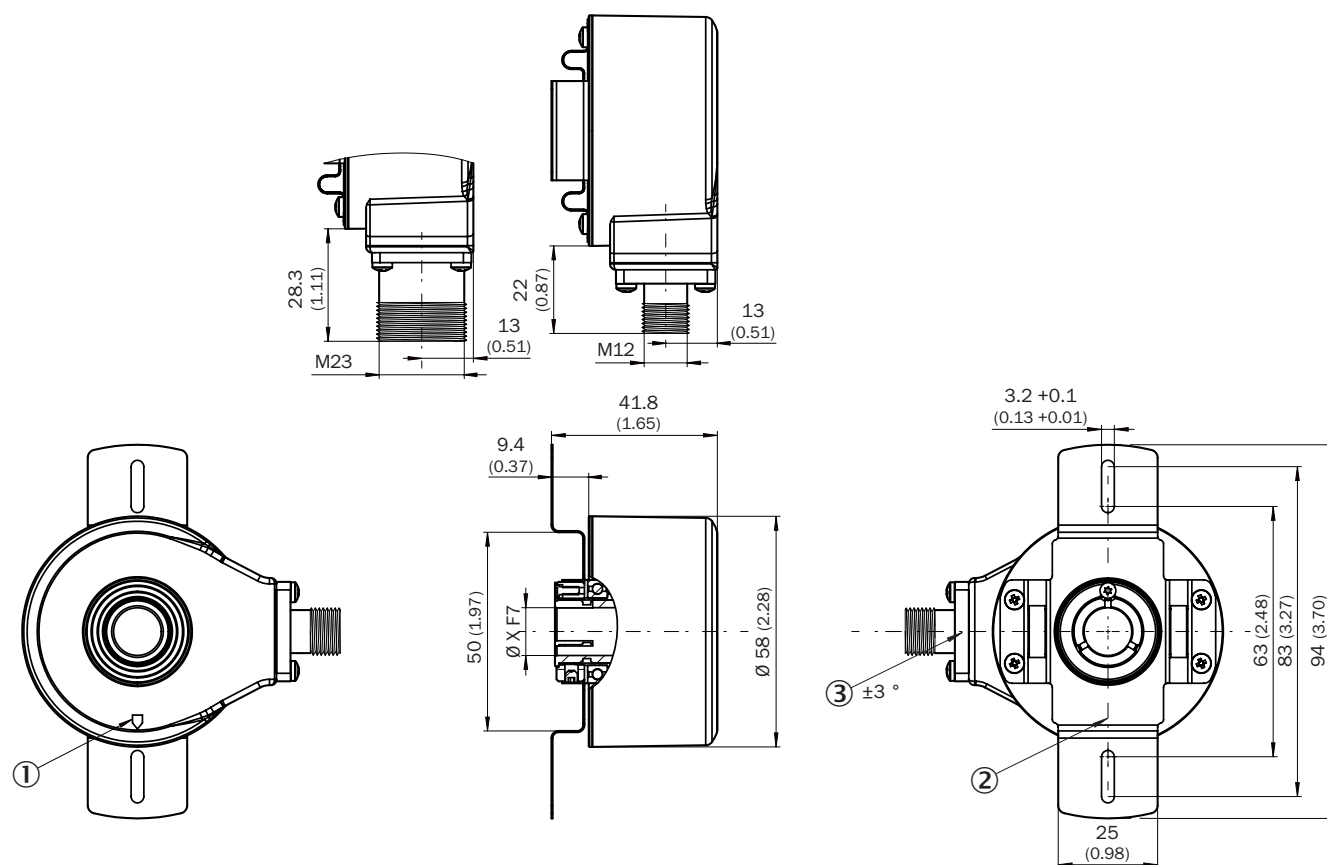
EU declaration of conformity	✓
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UK declaration of conformity	✓
ACMA declaration of conformity	✓
China-RoHS	✓
cRUus certificate	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing Through hollow shaft clamping at the front, male connector, 2-sided stator coupling, slot, screw hole circle 63–83 mm

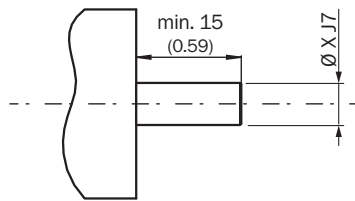


Dimensions in mm (inch)

- ① Zero pulse mark on housing
- ② zero pulse mark on flange under stator coupling
- ③ male connector tolerance in relation to hole pattern

TypeThrough hollow shaft with front clamping	Shaft diameter XF7
DBS60x-TAxxxxxxxDBS60x-T1xxxxxxx	6 mm
DBS60x-TBxxxxxxxDBS60x-T2xxxxxxx	8 mm
DBS60x-TCxxxxxxxDBS60x-T3xxxxxxx	3/8"
DBS60x-TDxxxxxxxDBS60x-T4xxxxxxx	10 mm
DBS60x-TExxxxxxxDBS60x-T5xxxxxxx	12 mm
DBS60x-TFxxxxxxxDBS60x-T6xxxxxxx	1/2"
DBS60x-TGxxxxxxxDBS60x-T7xxxxxxx	14 mm
DBS60x-THxxxxxxxDBS60x-T8xxxxxxx	15 mm
DBS60x-TJxxxxxxx	5/8"

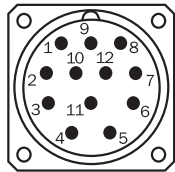
Attachment specifications Through hollow shaft with front clamping



customer side

TypeThrough hollow shaft with front clamping	Shaft diameter xJ7
DBS60x-TAxxxxxxxDBS60x-T1xxxxxxx	6 mm
DBS60x-TBxxxxxxxDBS60x-T2xxxxxxx	8 mm
DBS60x-TCxxxxxxxDBS60x-T3xxxxxxx	3/8"
DBS60x-TDxxxxxxxDBS60x-T4xxxxxxx	10 mm
DBS60x-TExxxxxxxDBS60x-T5xxxxxxx	12 mm
DBS60x-TFxxxxxxxDBS60x-T6xxxxxxx	1/2"
DBS60x-TGxxxxxxxDBS60x-T7xxxxxxx	14 mm
DBS60x-THxxxxxxxDBS60x-T8xxxxxxx	15 mm
DBS60x-TJxxxxxxx	5/8"
-	-

PIN assignment

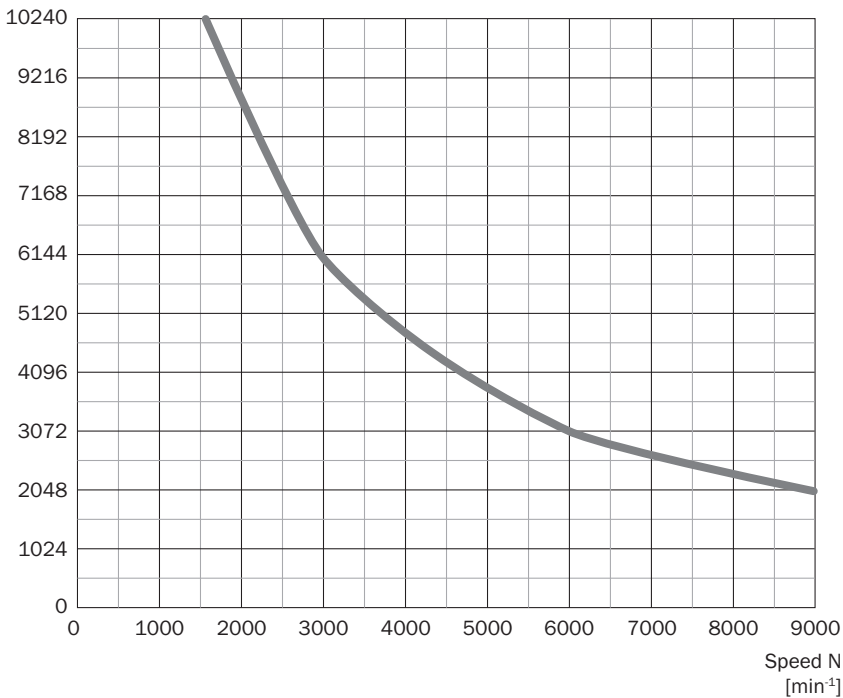


view of M23 male device connector on cable / housing

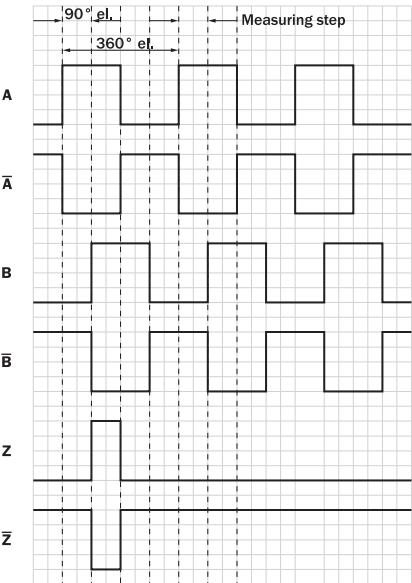
Wire colors (cable connection)	Male connector M12, 8-pin	Male connector M23, 12-pin	TTL/HTL 6-channel signal	Explanation
Brown	1	6	A-	Signal wire
White	2	5	A	Signal wire
Black	3	1	B-	Signal wire
Pink	4	8	B	Signal wire
Yellow	5	4	Z-	Signal wire
Purple	6	3	Z	Signal wire
Blue	7	10	GND	Ground connection
Red	8	12	+U _s	Supply voltage
-	-	9	Not assigned	Not assigned
-	-	2	Not assigned	Not assigned
-	-	11	Not assigned	Not assigned
-	-	7	Not assigned	Not assigned
Screen	Screen	Screen	Screen	Screen connected to encoder housing

Diagrams

Pulses per revolution



Diagrams Signal outputs for electrical interfaces TTL and HTL



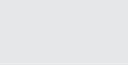
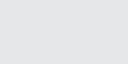
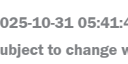
Cw with view on the encoder shaft in direction "A", compare dimensional drawing.

Supply voltage	Output
4,5 V ... 5,5 V	TTL
10 V ... 30 V	TTL
10 V ... 27 V	HTL

Supply voltage	Output
4,5 V ... 30 V	TTL/HTL universal
4,5 V ... 30 V	TTL

Recommended accessories

Other models and accessories → www.sick.com/DBS60

	Brief description	Type	part no.
connectors and cables			
	• Connection type head A: Flying leads • Connection type head B: Flying leads • Signal type: SSI, Incremental, HIPERFACE® • Items supplied: By the meter • Cable: 8-wire, PUR, halogen-free • Description: SSI, shielded, Incremental, HIPERFACE®	LTG-2308-MWENC	6027529
	• Connection type head A: Flying leads • Connection type head B: Flying leads • Signal type: SSI, Incremental • Items supplied: By the meter • Cable: 11-wire, PUR • Description: SSI, shielded, Incremental	LTG-2411-MW	6027530
	• Connection type head A: Flying leads • Connection type head B: Flying leads • Signal type: SSI, Incremental • Items supplied: By the meter • Cable: 12-wire, PUR, halogen-free • Description: SSI, shielded, Incremental	LTG-2512-MW	6027531
	• Connection type head A: Flying leads • Connection type head B: Flying leads • Signal type: SSI, TTL, HTL, Incremental • Items supplied: By the meter • Cable: 12-wire, UV and saltwater-resistant, PUR, halogen-free • Description: SSI, shielded, TTL, HTL, Incremental	LTG-2612-MW	6028516
	• Connection type head A: Female connector, M23, 12-pin, straight • Connection type head B: Flying leads • Signal type: Incremental • Cable: 30 m, 11-wire, PUR • Description: Incremental, shielded	DOL-2312-G30MLA3	2030702
	• Connection type head A: Female connector, M23, 12-pin, straight • Connection type head B: Flying leads • Signal type: Incremental • Cable: 25 m, 11-wire, PUR • Description: Incremental, shielded	DOL-2312-G25MLA3	2030699
	• Connection type head A: Female connector, M23, 12-pin, straight • Connection type head B: Flying leads • Signal type: Incremental • Cable: 20 m, 11-wire, PUR • Description: Incremental, shielded	DOL-2312-G20MLA3	2030695
	• Connection type head A: Female connector, M23, 12-pin, straight • Connection type head B: Flying leads • Signal type: Incremental • Cable: 15 m, 11-wire, PUR • Description: Incremental, shielded	DOL-2312-G15MLA3	2030692
	• Connection type head A: Female connector, M23, 12-pin, straight • Connection type head B: Flying leads • Signal type: Incremental • Cable: 10 m, 11-wire, PUR • Description: Incremental, shielded	DOL-2312-G10MLA3	2030688
	• Connection type head A: Female connector, M23, 12-pin, straight • Connection type head B: Flying leads • Signal type: Incremental • Cable: 7 m, 11-wire, PUR • Description: Incremental, shielded	DOL-2312-G07MLA3	2030685
	• Connection type head A: Female connector, M23, 12-pin, straight • Connection type head B: Flying leads • Signal type: Incremental • Cable: 2 m, 11-wire, PUR • Description: Incremental, shielded	DOL-2312-G02MLA3	2030682
	• Connection type head A: Female connector, M23, 12-pin, angled, A-coded • Signal type: HIPERFACE®, SSI, Incremental • Description: HIPERFACE®, shieldedSSIIncremental	DOS-2312-W01	2072580

	Brief description	Type	part no.
	• Connection systems: Solder connection • Connection type head A: Female connector, M23, 12-pin, straight, A-coded • Signal type: HIPERFACE[®], SSI, Incremental • Description: HIPERFACE[®], shieldedSSIIncremental • Connection systems: Solder connection	DOS-2312-G02	2077057
	Mounting systems		
	• Description: Bearing bracket for hollow shaft encoders, fastening screws included the Bearing Block is intended for very large radial and axial shaft loads. Particularly for application on: Belt pulleys, Chain pinions, Friction wheels. It is designed this way to enable fitting of encoder with blind hollow shaft with ø 12 mm. Operating speed max. 6,000 rpm⁻¹, axial shaft load 100 N, radial shaft load 100 N, bearing service life 3.6 x 10⁹ revolutions • Items supplied: Fastening screws included	BEF-FA-B12-010	2042728

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SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

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