

# SKS36-HFA0-K02-40

SKS/SKM36

**MOTOR FEEDBACK SYSTEMS** 



## SKS36-HFA0-K02-40 | SKS/SKM36

## MOTOR FEEDBACK SYSTEMS



## Ordering information

Туре	part no.
SKS36-HFA0-K02-40	1131702

Included in delivery: SKS36-HFA0-K02 (1)

Other models and accessories → www.sick.com/SKS\_SKM36

Illustration may differ

#### Detailed technical data

#### **Features**

M3 mounting screws for stator coupling not included with delivery.  Motor feedback system SKS36-HFA0-K02 (1034095). Packaging unit 40 pcs., Operating in-	
structions (part number: 8013452), 1 pc. per packaging unit.	

## Safety-related parameters

MTTF <sub>D</sub> (mean time to dangerous failure)	210 years (EN ISO 13849) <sup>1)</sup>
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<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 60 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Performance

Sine/cosine periods per revolution	128
Number of the absolute ascertainable revolutions	1
Total number of steps	4,096
Measuring step	$2.5{\rm ''}$ For interpolation of the sine/cosine signals with, e. g., 12 bits
Integral non-linearity	± 80 ", Error limits for evaluating sine/cosine period
Differential non-linearity	± 40 ", Non-linearity within a sine/cosine period
Operating speed	$\leq$ 12,000 min <sup>-1</sup> , up to which the absolute position can be reliably produced
Available memory area	1,792 Byte
System accuracy	± 120 "

#### Interfaces

Type of code for the absolute value	Binary
Code sequence	Increasing, when turning the shaft For clockwise rotation, looking in direction "A" (see dimensional drawing), For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
Communication interface	HIPERFACE <sup>®</sup>

## **Electronics**

Connection type	Male connector, 8-pin, radial
Supply voltage	7 V DC 12 V DC
Recommended supply voltage	8 V DC
Current consumption	60 mA <sup>1)</sup>

<sup>1)</sup> Without load.

Output	frequency	for sine	cosine signals	
Jacpac			Goome orginale	

≤ 65 kHz

## Mechanics

Shaft version	Tapered shaft	
Flange type / stator coupling	Spring mounting plate, stator coupling	
Dimensions	See dimensional drawing	
Weight	≤ 0.07 kg	
Moment of inertia of the rotor	4.5 gcm <sup>2</sup>	
Operating speed	12,000 min <sup>-1</sup> , 12,000 U/min	
Angular acceleration	$\leq 500,000 \text{ rad/s}^2$	
Operating torque	0.2 Ncm	
Start up torque	+ 0.3 Ncm	
Permissible movement static	± 0.1 mm, - 0.4 mm, + 0.2 mm radial, axial, axial	
Permissible movement dynamic	± 0.05 mm radial ± 0.1 mm axial	
Life of ball bearings	3.6 x 10 <sup>9</sup> revolutions	

## Ambient data

Operating temperature range	-20 °C +110 °C
Storage temperature range	-40 °C +125 °C, without package
Relative humidity/condensation	90 %, Condensation not permitted
Resistance to shocks	100 g, 6 ms, 6 ms (according to EN 60068-2-27)
Frequency range of resistance to vibrations	50 g, 10 Hz 2,000 Hz (EN 60068-2-6)
EMC	According to EN 61000-6-2 and EN 61000-6-3 <sup>1)</sup>
Enclosure rating	IP50, with mating plug inserted and closed cover (IEC 60529)

<sup>1)</sup> The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. The GND-(0 V) connection of the supply voltage is also grounded here. If other shielding concepts are used, users must perform their own tests.

#### Classifications

ECLASS 5.0	27270590
ECLASS 5.1.4	27270590
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270590
ECLASS 8.0	27270590
ECLASS 8.1	27270590
ECLASS 9.0	27270590
ECLASS 10.0	27273805
ECLASS 11.0	27273901
ECLASS 12.0	27273901
ETIM 5.0	EC001486
ETIM 6.0	EC001486

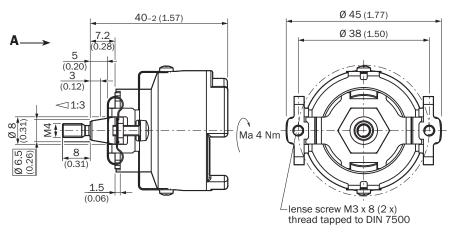
<sup>1)</sup> Without load.

## **SKS36-HFA0-K02-40 | SKS/SKM36**

MOTOR FEEDBACK SYSTEMS

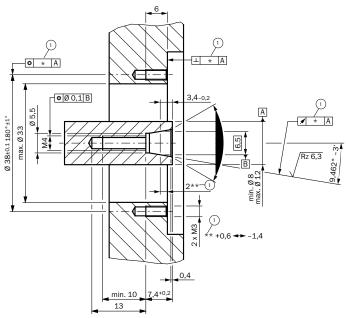
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

## Dimensional drawing General tolerances according to DIN ISO 2768-mk



Dimensions in mm (inch)

## Attachment specifications General tolerances according to DIN ISO 2768-mk

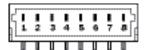


① The size of the tolerance reduces the permissible wave movement, see data sheet

## PIN assignment

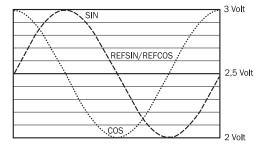
PIN	Signal	Colour of Wires	Explanation
1	$U_s$	red	Supply voltage 7 12 V
2	+ SIN	white	Process data channel
3	REFSIN	brown	Process data channel
4	+ COS	pink	Process data channel
5	REFCOS	black	Process data channel
6	GND	blue	Ground connection
7	Data +	grey or yellow	RS-485-parameter channel
8	Data -	green or purple	RS-485-parameter channel

The housing is electrically connected to the motor housing, via the stator coupling. The GND (0 V) connection of the supply voltage has no connection to the housing.



View of the plug-in face

# Diagrams Signal diagram for clockwise shaft rotation, looking in direction "A" (see dimensional drawing) $1 \text{ period} = 360^{\circ} : 128$



## Operation note Charactersitics applicable to all permissible environmental conditions

Signal	Values/unit
Signal peak, peak V <sub>SS</sub> of SIN, COS	0.8 V 1.1 V
Signal offset REFSIN, REFCOS	2.2 V 2.8 V

## Operation note Model-specific settings

Type-specific settings	SKS	SKM
Model ID (command 52h)	32h	27h
Free E <sup>2</sup> PROM [bytes]	1792	1792
Address	40h	40h
Mode_485	E4h	E4h
Codes 0 to 3	55h	55h
Counter	0	0

## Operation note Overview of status messages for HIPERFACE<sup>®</sup>

	Status code	Description	SKS	SKM
Error type	00h	The encoder has not detected any faults	•	•
Initialization	01h	Incorrect alignment data		•
	02h	Incorrect internal angular offset	•	
	03h	Data field partitioning table destroyed		
	04h	Analog limit values not available	•	
	05h	Internal I2C bus inoperative	•	-
	06h	Internal checksum error	•	•
Protocol	07h	Encoder reset occurred as a result of program monitoring	•	•
	09h	Parity error	•	
	0Ah	Checksum of transmitted data is incorrect	•	
	0Bh	Unknown command code	•	•
	0Ch	Number of transmitted data is incorrect	•	•
	0Dh	Transmitted command argument is not allowed	•	•
Data	0Eh	The selected data field may not be written to		
	0Fh	Incorrect access code	•	
	10h	Size of specified data field cannot be changed	•	
	11h	Specified word address lies outside the data field	•	-
	12h	Access to non-existent data field	•	•
Position	01h	Analog signals outside specification		
	1Fh	Speed too high, no position formation possible		
	20h	Singleturn position unreliable	•	
	21h	Multiturn position error		•
	22h	Multiturn position error		•
	23h	Multiturn position error		
Other	1Ch	Value monitoring of the analog signals (process data)		
	1Dh	Transmitter current critical or P2RAM-Error	•	
	1Eh	Encoder temperature critical	•	
	08h	Counter overflow	•	
	For more inform	mation on the interface see HIPERFACE $^{ ext{@}}$ - $ ext{description}$ , part no. $8010$	701	

## Operation note Overview of supported commands for HIPERFACE<sup>®</sup>

Overview of supported commands		SKS	SKM	
Command byte	Function	Code 0 1)	Comments	Comments
42h	Read position		12 bits	24 bits
43h	Set position			
44h	Read analog value		Channel number F0H 48h	Channel number F0H 48h
			Temperature [°C]	Temperature [°C]
46h	Read counter			
47h	Increment Counter			
49h	Delete counter	-		
4Ah	Read data			
4Bh	Store data			
4Ch	Determine status of a data field			
4Dh	Create data field			
4Eh	Determine available memory area			
4Fh	Change access code			
50h	Read encoder status			
52h	Read out type label		Encoder type = 32h	Encoder type = 37h
53h	Encoder reset			
55h	Allocate encoder address	-		
56h	Read serial number and program version			
57h	Configure serial interface	-		
6AH	Set position with synchronization to process data channel			

<sup>&</sup>lt;sup>1)</sup> The commands thus marked include the parameter "Code 0". Code 0 is a byte inserted into the protocol to provide additional protection of vital system parameters against accidental overwriting. When the device is supplied, "Code 0" = 55h.

#### Recommended accessories

Other models and accessories → www.sick.com/SKS\_SKM36

	Brief description	Туре	part no.		
programming	devices				
[or i	<ul> <li>Product segment: Programming devices</li> <li>Product family: PGT-11-S</li> <li>Description: SVip® LAN programming tool for all motor feedback systems</li> <li>Items supplied: 1x programming tool PGT-11-S LAN, 1x power supply unit 100-240 V AC / 12 V DC, primary adapter (Europe, UK, USA/Japan, Australia), Ethernet cable 3 m</li> </ul>	PGT-11-S LAN	1057324		
Mounting systems					
	Description: Mounting tools	BEF-MW-SKX36	2031079		
connectors and cables					
	Connection type head A: Female connector, JST, 8-pin, straight Connection type head B: Flying leads Signal type: HIPERFACE® Cable: 0.2 m, 8-wire Description: HIPERFACE®, unshielded	DOL-0J08-G0M2XB6	2031086		

## SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is "Sensor Intelligence."

## **WORLDWIDE PRESENCE:**

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